Decidable fragments of first order modal logic

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- The work reported here is joint with Anantha Padmanabha (IRIF, Paris) and Yanjing Wang (PKU, Beijing).

Summary-1

Church - Turing 1936: First order logic is undecidable.

- The classical decision problem: identify the decidable syntactic fragments of first order logic. A successful project of the twentieth century.
- Syntactic restrictions: quantifier prefix classes, restrict number of variables, scope of quantifiers, etc.
- Semantic restrictions: constraints on models by fixing interpretation of predicates; theories of order, arithmetical theories, algebraic theories, combinatorial theories, etc.
- Once we find decidable fragments, we seek to extend them with non-FO-definable constructs maintaining decidability: e.g. fixed-point extensions, set quantification.

Summary-2

Propositional modal logics are extensively used in computer science for specification and verification.

- Many extensions of modal logics are decidable.
- Vardi, 1996: Why are modal logics so robustly decidable ?
- Perhaps because they sit inside the two-variable fragment of First order logic (which is decidable)?
- Andreka, van Benthem, Nemeti: Because they correspond to a guarded fragment of First order logic.

Summary-3

Kripke 1962: First order modal logic (FOML) is undecidable, even with a single monadic predicate, with no equality, constants or function symbols.

- Fischer-Servi *et al*, Segerburg 1978: One-variable fragment is decidable.
- In the last few years: the monodic fragment, some bundled fragments and fragments of Term-modal logics (guarded, two-variable) are decidable.
- The good news: these results indicate that there is plenty out there for those who care to dig!
- Proceed with caution, though: even addition of a few constants can make the big difference.

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- Every element is dominated by another: A good first order sentence.
- All processes have terminated: a contingent, but stable proposition.
- Every request is eventually granted: modal proposition, interpreted as temporal or reachability.
- Every dominated element can become the dominator:

$$\forall x. [(\exists y. x < y) \supset \Diamond (\forall y. x \ge y)]$$

Propositional modal logic

The extension of propositional logic with a unary operator. • Syntax:

$$p \in P \mid \neg \alpha \mid \alpha \lor \beta \mid \Box \alpha$$

- $\Box \alpha$ is read as α holds necessarily.
- Its dual, $\Diamond \alpha = \neg \Box \neg \alpha$ is read as α holds possibly.

Possible worlds semantics

Also called Kripke Structures: M = (W, R, V): • $R \subseteq (W \times W), V : W \rightarrow 2^{P}.$

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Also called Kripke Structures: M = (W, R, V):

- $R \subseteq (W \times W), V : W \rightarrow 2^{P}.$
- $M, w \models p$ if $p \in V(w)$, for $p \in P$.
- $M, w \models \Box \alpha$ if for all w' such that w R w', $M, w' \models \alpha$.
- It is easily seen that M, w ⊨ ◊α if for some w' such that w R w', M, w' ⊨ α.
- α is satisfiable if there exists a model M = (W, R, V) and w ∈ W such that M, w ⊨ α.

Good properties

Has good model theoretic and algorithmic properties.

- A fragment of first order logic.
- Map α to α^* of FOL:

$$\Diamond \alpha \longrightarrow \exists y : (E(x, y) \land \alpha^*(y)) \Box \alpha \longrightarrow \forall y : (E(x, y) \supset \alpha^*(y))$$

- Satisfiability: PSpace-complete.
- Model checking: $O(\mathcal{K} \cdot \alpha)$.

Limitations of modal logic

Modal logic is very weak in terms of expressive power.

- No equality: We cannot say that both an *a*-transition and *b*-transition from the current state lead us to the same state.
- Bounded quantification: We cannot say that a property holds in all states.
- New transitions not definable: For instance, we cannot define $E(x, y) = E_a(y, x) \wedge E_b(y, x)$.

More limitations

More on the list of complaints.

- No counting: We cannot say that there is at most one *a*-transition from the current state (and hence cannot distinguish deterministic systems from nondeterministic ones).
- No recursion: We can look only at a bounded number of transition steps. This is a limitation shared by FOL as well.

And yet, modal logic is interesting, on many counts.

In praise of modal logic

It has interesting model theoretic properties.

• Invariance under bisimulation:

$$(\mathcal{K}, \mathbf{w} \models \alpha \land (\mathcal{K}, \mathbf{w}) \sim (\mathcal{K}', \mathbf{w}') \Longrightarrow (\mathcal{K}', \mathbf{w}') \models \alpha$$

- In fact, ML is the bisimulation invariant fragment of FOL.
- It has the finite model property.
- It has the tree model property.

Extensions

Numerous extensions of ML, designed to overcome the limitations mentioned, still with similar model theoretic and algorithmic properties.

- PDL = ML + transitive closure.
- LTL = ML + temporal operators on paths.
- *CTL* = *ML* + temporal operators on paths + path quantification.
- μ-calculus: encompasses these and others like game logics and description logics.

Robustness

All these extensions have good algorithmic properties. The following hold for the μ -calculus, which encompasses most modal logics of computation.

- Satisfiability is Exptime-complete.
- Efficient model checking for many subclasses; in general, is in $NP \cap co NP$.
- Bisimulation invariant fragment of monadic second order logic.

Vardi's question

- Vardi, 1996: Why are modal logics so robustly decidable ?
- The standard translation from ML to FO does not need more than two free variables.
- Traditionally, this has been used as an explanation for why ML has good properties.
- Is this explanation convincing ?

Fixed variable FO

- FO^k : relational fragment of FOL with only k free variables.
 - "There exists a path of length 17" is in FO^2 :

 $\exists x \exists y (E(x, y) \land \exists x (E(x, y) \land \exists y (E(x, y) \land \ldots \exists y E(x, y)) \ldots))$

- The satisfiability problem is undecidable for FO^k, for all k ≥ 3.
- This is true even for most of the prefix classes.

Two variable FO

- Scott 1962: *FO*² without equality can be reduced to the Gödel class and is hence decidable.
- Mortimer 1975: *FO*² has the finite model property, and is decidable.
- Grädel, Kolaitis, Vardi, 1997: *FO*² satisfiability is NExptime complete. (Lower bound essentially from Fürer 1981.)
- FO² is not nearly as robustly decidable as modal logic, lacks the tree model property: consider ∀x∀y.E(x, y).

A closer look

A closer look at the translation from ML to FOL shows not only the use of two variable logic, but also $\exists x.(E_a(x,y) \land \ldots)$ and $\forall x.(E_a(x,y) \Longrightarrow \ldots)$.

- Thus quantifiers are always relativized by atoms in the modal fragment of FOL.
- Each subformula can "speak" only about elements that are 'close together' or guarded.
- Guarded fragment: Quantification is of the form: $\exists x.(\alpha(x,y) \land \phi(x,y)) \text{ and } \forall x.(\alpha(x,y) \implies \phi(x,y)).$ α is atomic and contains all the free variables in ϕ .

A challenge

- Andréka, van Benthem, Nemeti 1998: The guarded nature of quantification in modal logics is the "real" reason for their good algorithmic and model theoretic properties.
- Results proved since then provide some positive evidence.

Natural directions

All this wisdom suggests similar approaches to First order modal logic.

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All this wisdom suggests similar approaches to First order modal logic.

- We would like to combine the best practices of FO and the elegances of ML.
- Unfortunately, FOML seems to combine the worst of the two, even in its simplest versions.

First order logic

Let *Var* denote the set of variables. A vocabulary is a pair (C, \mathcal{P}) , where *C* is a set of constant symbols and \mathcal{P} is a set of predicate symbols with arity. Let $T = Var \cup C$ denote the set of terms.

• Syntax:

$$P^m(t_1,\ldots,t_m) \mid t = t' \mid \neg \alpha \mid \alpha \lor \beta \mid \forall x.\alpha$$

 Model: M = (D, ι, π) where π : Var → D, ι_c : C → D and ι_P maps predicate symbol P^m to a map D^m → {0, 1}.

•
$$\hat{\pi}: T \to D: \hat{\pi} = \iota_c \cup \pi.$$

The natural combination of First order and modal logics.

• Syntax:

$$P^{m}(t_{1},...,t_{m}) \mid t = t' \mid \neg \alpha \mid \alpha \lor \beta \mid \forall x.\alpha \mid \Box \alpha$$

- But the semantics is more complicated now!
- With every world we need to associate a first order structure, and interpret terms as elements of that structure.
- Statutory warning: This can get quite chaotic.

Coherence across worlds

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• Is it reasonable to fix a single domain *D* for the entire 'universe' of possibilities?

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- Is it reasonable to fix a single domain *D* for the entire 'universe' of possibilities?
- Constant domain interpretation, as opposed to Varying domain interpretations: in the latter all quantification is over "current" domain.
- But how do you interpret (even) □(P(x) ∨ ¬P(x)), where x is free? Suppose that x evaluates to d in the current world, but d does not exist in an accessible world.
- One solution is to impose a monotonicity condition. If *d* exists at *w* and *wRw'* then *d* exists at *w'*.

Constant domain interpretations generalize smoothly from modal logics.

 Model M = (W, D, R, ι, ρ, π) with ι : C → D, π : Var → D and ρ_P maps predicate symbol P^m to a map (W × D^m) → {0,1}.

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- Is the formula $\Box \forall x \alpha \supset \forall x . \Box \alpha$ valid?
- The formula $\forall x. \Box (\exists y. x = y)$ is valid.
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- Kripke 1962 reduces this problem to satisfiability of FOML formulas with unary predicates.
- $\tau(Q(x,y)) = \Diamond(P(x) \land R(y)).$
- $\tau(\neg \alpha) = \neg(\tau(\alpha)).$

•
$$\tau(\alpha \lor \beta) = \tau(\alpha) \lor \tau(\beta).$$

- $\tau(\exists x.\alpha) = \exists x.\tau(\alpha)).$
- It is easy to see that α is FO-satisfiable iff $\tau(\alpha)$ is FOML-satisfiable.

The tale of woe

Wolter and Zakharyaschev 2001 lament:

- The monadic fragment of practically all predicate modal logics is undecidable.
- The two variable fragment of practically all predicate modal logics is undecidable, even with constant domain interpretations, without equality and constants.
- This leaves only the inexpressive one variable fragment as decidable.

The monodic fragment

Wolter and Zakharyaschev study the monodic fragment.

• All undecidability proofs of modal predicate logics exploit formulas of the form 2 (x; y) in which the necessity operator applies to subformulas of more than one free variable; in fact, such formulas play an essential role in the reduction of undecidable problems to those fragments.

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- Monodic formulas are those in which only one variable may occur free in the scope of any modality.
- They show that if we consider most well-behaved decidable fragments of FO, then their monodic lifting to FOML is decidable.

Modal scope

Monodic formulas look suspiciously like one-variable formulas but they are not; they are more expressive.

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- $\Diamond(P(x) \land \exists y.Q(x,y))$ is monodic but not 1-variable.
- ∃x.∀y.R(x, y) is a monodic sentence but not expressible in the 1-variable fragment.

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- Now we can set up an argument by induction on modal depth, building the model level by level from the "leaves" to the root.
- The realised types need to be combined carefully. For instance consider the formula ∃y.(□P(y) ∧ ◊∃x.¬P(x)).

We see that in the undecidability proof we used the modality as an additional quantifier. The idea of bundling modalities and quantifiers is to limit this capability.

• Consider the syntax:

 $P(\bar{\mathbf{x}}) \mid \neg \alpha \mid \alpha \lor \beta \mid \exists \mathbf{x} \Box \alpha \mid \forall \mathbf{x} \Box \alpha$

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- ∀x◊.∃y□R(x, y): Every element can be updated in such a way that another can necessarily dominate it.
- The ∃x□ fragment was developed by Yanjing Wang in the context of epistemic logic to study Knowing how, and he went on to unify many such modalities.

Algebra Co-algebra Seminar, ILLC, Amsterdam

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- The latter is undecidable for constant domain interpretations even with only monadic predicates. (The Kripke coding, with some subtlety.)
- The former is PSpace-complete for constant domains even allowing arbitrary predicates.
- Interestingly the fragment with both bundles is PSpace-complete over varying domain with arbitrary predicates.

Varying domains

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Varying domains

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- Increasing domain semantics enables us to easily add new witnesses as we need.
- One complication: we need to add witnesses for existential quantifiers and successor worlds simultaneously, as any decision for one affects the choice of the other.
- We can then show that the ∃□ bundle cannot distinguish between constant and increasing domains, so we can "guess" sufficiently many witnesses at one go and use them as we need.

Term-modal logics

Introduced by Fitting, Thalmann and Voronkov in 2001.

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- ∃x.∀y.(Wit(x) ⊃ □_xKilled(x, Mary): All witnesses know who killed Mary.
- Note that we now have a logic with an unbounded vocabulary: the number of relation symbols can be infinite.
- For us, this study again came up in the context of epistemic logic, to study reasoning in the context of unboundedly many agents (and in a related sense, in games with unboundedly many players).

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- In fact even the propositional fragment is undecidable.
- Padmanabha shows that PTML is as expressive as TML; indeed this holds even for the two-variable fragment.

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Translation of TML into FOML

We can translate TML into FOML.

- $\tau(\Diamond_x \alpha) = \Diamond(E(x) \wedge \tau(\alpha)).$
- This preserves monodicity and hence many of the earlier results give decidable fragments.

PTML is as hard as TML

PTML is the propositional fragment of TML.

•
$$\tau(P_i(x_1,\ldots,x_n)) = \Diamond_{x_1}(\neg q \land \Diamond_{x_2}(\ldots \neg q \land \Diamond_{x_{n_i}}(\neg q \land p_i)\ldots))$$

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• $\tau(\Box \phi) = \Box (q \Longrightarrow \tau(\phi))$

•
$$\tau(\Box_x \phi) = \Box_x(q \implies \tau(\phi)).$$

•
$$\tau(\exists_{\mathsf{x}}\phi) = \exists_{\mathsf{x}}(q \wedge \tau(\phi)).$$

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$$\tau(\Box_x \phi) = \Box_x(q \implies \tau(\phi)).$$

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 The translation preserves the number of variables, quantifier rank, and modal depth increases only linearly.

Two variables

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Interestingly, the two variable fragment of TML is decidable.

- This again proceeds by constructing a tree model from root to leaf.
- It is an induction on modal depth, where at each level, the FO^2 model construction is used.
- An analogue of Scott Normal Form is used, and the use of realised types and 'model gluing' is tricky.

The proof steps involved in showing that the FO^2 fragment has the bounded model property.

 Every sentence φ ∈ FO² has an equi-satisfiable sentence in Scott Normal Form: ∀x.∀y.α ∧ ∧(∀x.∃y.β_j) where α

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For a given FO structure A and elements c, d in it, the 2 - type(c, d) = (Γ₁, Γ₂) which are the set of atoms true in A by mapping the variables x, y to (c, d) and (d, c).

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- Given ϕ in SNF satisfiable in A, we can build a bounded model based on 1 type(A).

We have normal forms for FO^2 and for modal logic.

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- Scott Normal Form: ∀x.∀y.α ∧ ∧ ∧ (∀x.∃y.β_j) where α and the β_j's are quantifier free (by introducing new predicates).
- For propositional modal logic we have (a normal form due to Kit Fine): DNF where every clause is of the form
 (Λ s_i) ∧ □α ∧ Λ ◊β_j where s_i are literals and α and the
 β_js are quantifier free.

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- Scott Normal Form: ∀x.∀y.α ∧ ∧ ∧ (∀x.∃y.β_j) where α and the β_j's are quantifier free (by introducing new predicates).
- For propositional modal logic we have (a normal form due to Kit Fine): DNF where every clause is of the form
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We need to combine the two for $PTML^2$.

Fine Scott Normal form for *PTML*²

Below let z range over $\{x, y\}$.

• For $PTML^2$ we have formulas in DNF where each clause is of the form $\sigma_1 \wedge \sigma_2$ where:

•
$$\sigma_1 = (\bigwedge_i s_i) \land \bigwedge_z (\Box_z \alpha \land \bigwedge_j \Diamond_z \beta_j)$$

• $\sigma_2 = \bigwedge_z (\forall z.\gamma \land \bigwedge_k (\exists z.\delta_k)) \land \forall x.\forall y.\phi \land \bigwedge_m (\forall x.\exists y.\psi_m)$

• Here α and the β_j s are recursively in the normal form, $\gamma, \phi, \delta_k, \psi_\ell$ are all quantifier free and every modal formula occurring in them is recursively in the normal form.

Strategy: For a $PTML^2$ formula satisfiable in a tree model, inductively come up with bounded agent models for every subtree of the given tree (based on types), starting from leaves to the root.

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- The central idea is that this transformation preserves *PTML*² formula satisfiability.

Decision procedure

The model construction outlined proves a bounded agent property.

- We show that ϕ is satisfiable iff it is satisfiable in a model whose domain is of size $\leq 2^{2^{|\phi|}}$.
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- We show that ϕ is satisfiable iff it is satisfiable in a model whose domain is of size $\leq 2^{2^{|\phi|}}$.
- So we get a 2 ExpSpace algorithm for satisfiability.
- There is a *NExpTime* lower bound for *FO*².

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Implicit quantification

A variable-free modal logic.

- $[\forall]\alpha$ asserts α for every x-successor for every x.
- $[\exists]\alpha$ asserts α for every x-successor for some x.
- IQML is exactly the propositional bundled fragment of TML.

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- Adding equality, the logic lacks the finite agent property.
- Significant gap between lower bounds and upper bounds.
- We have decidability for systems with infinite sets of agents, where they form a regular set.

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- Many questions remain: equality is intriguing.
- Model classes, correspondence theory: mostly open.
- Expressiveness of different logics needs to be carefully pinned down.

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